

Odometers and Clocks in Introductory Relativity

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Abstract

There are two ways of formulating the essential ideas of special relativity:

a) The *contraction/dilation* approach alleges that rulers contract and clocks run more slowly when moving relative to the observer.

b) In contrast, the *geometric* approach emphasizes the proper length measured by odometers and the proper time measured by ordinary clocks. These properties are intrinsic to the odometers and clocks, unaffected by the motion of this-or-that observer.

The geometric approach has so many advantages – in terms of simplicity, power, elegance, and consistency – that one wonders why anybody would bother with the other approach.

The geometric approach treats space and time on the same footing, and treats rotations and boosts on the same footing. As a consequence we see an ordinary clock as being more similar to an odometer than to a rigid ruler.

Relativity should not be considered weird or paradoxical; it is just the geometry of spacetime. A good qualitative understanding of the essential ideas can be achieved just by using diagrams to show the correspondence between spacetime and ordinary space. This does not require much beyond high-school notions of geometry, trigonometry, and vectors.

Additional keywords: FitzGerald-Lorentz contraction, time dilation, time dilatation, intrinsic length, invariant length, invariant mass, chord length, chord time, inertial navigation system, twin “paradox.”

I. INTRODUCTION

It is common to have two or more contrasting ways of describing the same physics. Two descriptions that make more-or-less equivalent predictions may nevertheless be quite different conceptually and pedagogically.

Scenario #1: Feynman¹ presented a pair of contrasting qualitative descriptions of general relativity.

- a) In one description, the space is flat, but the length of the ruler varies as a function of position.
- b) In the other description, the length of the ruler is invariant, but the space is curved.

In this scenario, description (a) is little more than a parable, useful only for a limited range of pedagogical purposes. Within its limitations, its predictions are in qualitative agreement with description (b), but it cannot withstand scrutiny. For quantitative work, we are vastly better off describing general relativity in terms of invariant rulers in a curved space.

Note that these two descriptions should not be used at the same time. If you posit enough ruler-distortion to account for the physics, and additionally posit enough curvature to account for the physics, that would be overdoing it. Perhaps you could describe half the physics one way and half the other way, but this would be pointless and unnecessarily complicated.

Scenario #2: The history of special relativity furnishes another pair of contrasting descriptions:

- a) In the early days, it was conventional to say that the mass of an object was greater if it was moving relative to the observer. This is called “relativistic mass”
- b) Nowadays it is more conventional to say that mass is invariant, i.e. independent of the choice of the observer. It is an intrinsic property of the object.

The modern view can be understood by reference to the following very important equation:

$$m^2 c^4 = E^2 - p^2 c^2 \tag{1}$$

$$m^2 = E^2 - p^2 \quad \text{in units where } c = 1 \tag{2}$$

where p is the 3-momentum. Note that equation (2) has an elegant interpretation in terms of the dot product of the 4-momentum with itself.

We see that mass and energy are not “the same thing.” Energy is energy (E), and mass is mass (m). Mass tells us the *rest energy*, as in equation (3). That is, $E = m$ when $p = 0$ – and not otherwise.

$$E_{\text{rest}} = m c^2 \tag{3}$$

It is a common misconception to think that mass is occasionally converted to “energy” in such a way that the energy (E) is not conserved. The modern view is that mass is part of the energy, and always has been, although it was not *recognized* as such until the 20th century. Therefore we say that mass (aka rest energy) is occasionally converted to *some other form* of energy, such that the overall energy is strictly conserved.

One problem with the idea of “relativistic mass” is that there are at least three inequivalent ways of defining it. One approach is to define it as E/c^2 where E is the total energy, in contrast the invariant mass E_{rest}/c^2 in accordance with equation (3). Using this approach, the “relativistic mass” is greater than the plain old mass by a factor of γ , where:

$$\gamma := \frac{E}{E_{\text{rest}}} = \frac{dt}{d\tau} \tag{4}$$

Another attempt to define “relativistic mass” starts from the claim that mass “must” increase, because mass measures “resistance to acceleration,” and a fast-moving particle is observably more resistant to acceleration than its “rest mass” alone would predict. For straight-line acceleration, we find that this “relativistic mass” is greater than the plain old mass by a factor of γ cubed. This is confusing, to say the least, because it conflicts with the previous paragraph, which involved only γ to the first power.

It is much simpler to just forget the idea of relativistic mass. As discussed in Ref. 2, it is perfectly possible to understand the relativistic decrease in the 3-acceleration without mentioning mass at all. The 3-acceleration can be seen to be smaller than the spacelike part of the proper acceleration for reasons having nothing to do with mass, merely to do with projections and the geometry of spacetime.

A third approach to “relativistic mass” uses circular motion, unlike the the straight-line motion considered above. As discussed in Ref. 2, this gives yet another numerical value for the “relativistic mass,” conflicting with both of the previous attempts. It’s not very convenient to have a “relativistic mass” that depends on direction. Mass should be a scalar.

Given this threefold inconsistency and other problems, it makes sense to forget about “relativistic mass.” The modern, sensible approach is to describe the physics in terms of the invariant mass, intrinsic length, and proper time. Then at the end of the day, the solution can be projected onto the laboratory frame if necessary.

In passing we remark that the shift in emphasis from (a) to (b) was accompanied by a shift in terminology. Nowadays experts (and many non-experts as well) conventionally speak of “the” mass of the proton as being about 1 amu. It would be redundant to call this the “rest” mass or the “invariant” mass; we just call it the mass. In contrast, some³ (but not all) early references spoke of non-constant masses. In any case, we do not wish to argue about terminology; the contrasting ideas are more important than the conflicting terminology.

Scenario #3: We now come to the central topic of this article, namely contrasting descriptions of length and time:

- a) One description alleges that rulers are shorter when they are moving relative to the observer; this is known as the FitzGerald-Lorentz contraction.^{4,5} It also alleges that clocks run more slowly when they are moving relative to the observer; this is called time dilation or time dilatation.⁶
- b) The other description focusses attention on the intrinsic length of rulers and the proper time of ordinary clocks.

Either of these descriptions – if you get the details right – can be used to predict and/or describe the correct physics. But it would be incorrect to use both of them at the same time. Either the ruler gets shorter or it doesn’t; you can’t have it both ways.

When choosing which description to use, one should consider such factors as simplicity, elegance, power, and compatibility with other descriptions and models.

Note: We will make heavy use of the idea of *spacetime* – rather than space or time separately – as originated in Ref. 7. We will also make use of the correspondence between rotations and boosts. A good discussion of these simple yet powerful ideas can be found in Ref. 9. Another discussion of the correspondence between rotations and boosts can be found in Ref. 10.

Also note: In this article, the term “vector” will always refer to a *physical vector*, which is a physical object unto itself, existing in space or spacetime. This is in contrast to any notion

of a vector being defined as a list of components. If you switch from one reference frame to another, the physical vector stays the same, but the components change, as discussed in Ref. 11.

By the way: In expressions such as “proper time,” the word “proper” means “its very own,” as in “proprietary.” (Other meanings of the word, e.g. “correct” or “appropriate,” are not relevant here.)

Historical note: The idea that rulers contract was proposed^{4,5} even before there was a complete theory of special relativity. Einstein’s first relativity paper¹² included the idea of clocks that run more slowly when moving. The geometric approach was developed⁷ a short time later.

II. PROPER LENGTH

To understand what we mean by proper length, consider figure 1. It shows two rulers, each 12 inches long. The ruler on the left is seen face-on by observer Joe, whose lines of sight are shown using blue, dashed lines. Joe sees the other ruler somewhat end-on, so that it is foreshortened by a factor of 3-to-1. This example involves only ordinary Euclidean geometry; the analogy to relativity will become apparent soon.

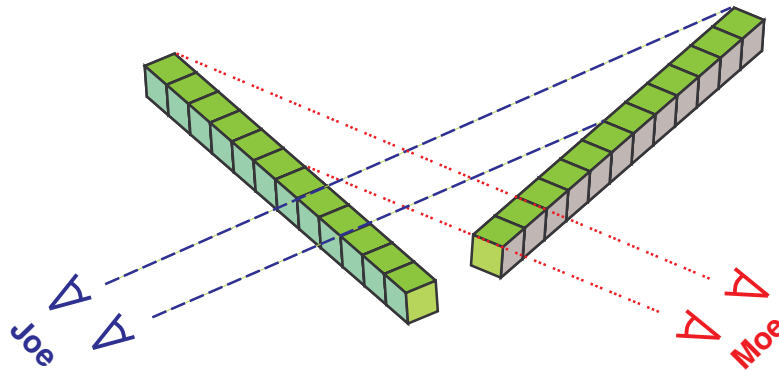


FIG. 1: Foreshortening

The foreshortening is symmetrical, in the sense that Moe (whose lines of sight are shown using red, dotted lines) sees the ruler on the right face-on, and sees ruler on the left somewhat end-on, foreshortened by the same 3:1 factor.

The point here is that ordinary rulers have a well-understood property we call *length*. When we view a ruler somewhat end-on, we do *not* conventionally say that its length has changed. We might say that the ruler *appears* foreshortened, or that the *projection* of the ruler onto our field of view is foreshortened ... but “the” length is an intrinsic property of the ruler, and is invariant with respect to rotations.

We now wish to show the correspondence between ordinary geometry (typeset on the left side of the page) and relativity (typeset on the right side of the page). One might be tempted to assume that foreshortening is analogous to the FitzGerald-Lorentz contraction, but that is not quite correct, as we shall see.

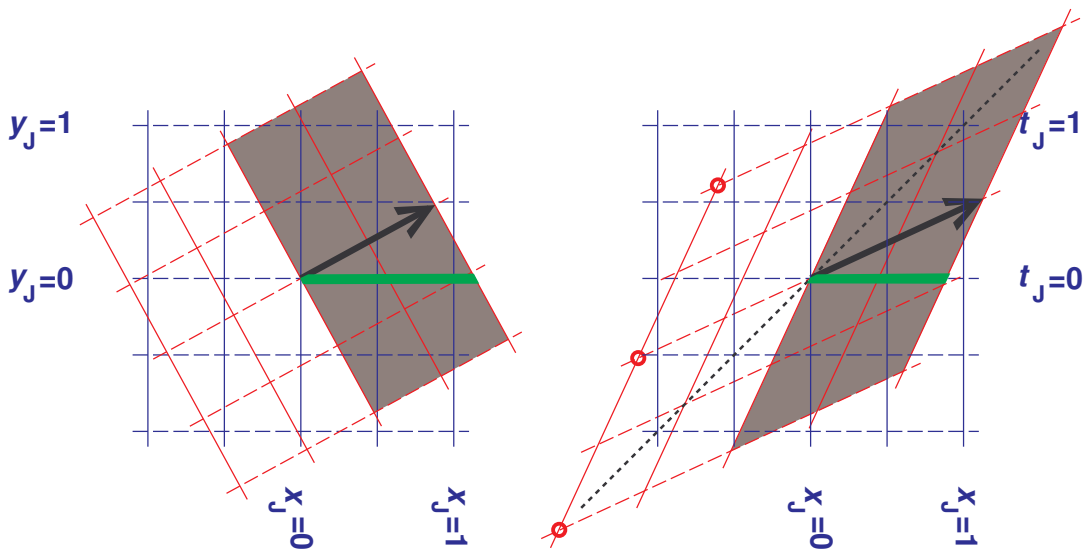


FIG. 2: FitzGerald-Lorentz Contraction

Suppose we have a long piece of fabric, as represented by the gray area on the left side of figure 2. It is 1 meter wide, as represented by the black arrow.

We lay the fabric across the table at some angle θ (the Greek letter theta), on the order of $\theta = 0.5$ radians.

Suppose we have a stick that has existed for a long time, and will continue to exist for a long time, as represented by the gray area on the right side of figure 2. The stick is 1 meter long, as represented by the black arrow.

We boost it, so that it is moving relative to Joe’s reference frame with some rapidity ρ (the Greek letter rho), on the order of $\rho = 0.5$.

We make a cut parallel to the edge of the table, as shown by the heavy green bar at location $y_J = 0$. How long will the cut be? Well, it will be longer than 1 meter. This is the opposite of foreshortening! The diagonal cut is longer (not shorter) than the proper width.

If somebody asks about “the” width of the fabric, you should answer that the width is 1 meter. This is the proper width of the fabric. It is intrinsic to the fabric, independent of its orientation relative to this-or-that table.

When we rotate the fabric, the diagonal-cut distance gets longer, but that does not mean the fabric got wider. The lengthening of the diagonal cut is not a property of the fabric; it is a property of the geometry of the situation.

Simple foreshortening (as shown in figure 1 for example) is not a perfect analogy for the FitzGerald-Lorentz contraction. That’s because it emphasizes orthogonal projections. You can see on the left side of figure 2 that the x_J component of the black vector has *less* than unit length, since the arrow starts at $x_J = 0$ and falls short of crossing the $x_J = 1$ contour. This is in contrast to the heavy green bar, i.e. the diagonal-cut length, which has *more* than unit length.

We ask Joe to take a snapshot of the stick at time $t_J = 0$, as shown by the heavy green bar. What is the length of the image he records? Well, it will be less than 1 meter, i.e. less than the proper length of the stick. This is the famous FitzGerald-Lorentz contraction.

If somebody asks about “the” length of the stick, you should answer that the length is 1 meter. This is the proper length of the stick. It is intrinsic to the stick, independent of its motion relative to this-or-that observer.

When we boost the stick, the snapshot image size gets shorter, but that does not mean that the stick got shorter. The FitzGerald-Lorentz contraction is not a property of the stick; it is a property of the spacetime geometry of the situation. Orthogonal projections do not suffice to explain the FitzGerald-Lorentz contraction. You can see on the right side of figure 2 that the x_J component of the black vector has *more* than unit length, since the arrow starts at $x_J = 0$ and extends past the $x_J = 1$ contour. This is in contrast to the heavy green bar, i.e. the snapshot length, which has *less* than unit length. See section III for more details about projections.

Note: We are talking about a sophisticated sort of snapshot here. Joe makes use of a whole array of assistants, spread out along a contour of constant time in Joe’s frame. They answer questions about *events* in spacetime: Is there a piece of stick *at your location right now*? This sophisticated snapshot is immune from the Penrose-Terrell aberration that would plague pictures taken with a simple box camera.

At present, it is fairly common for general-education textbooks to suggest that the snapshot length, i.e. the FitzGerald-Lorentz-contracted length, should be considered “the” length of the stick. However, we predict that over time, this will change, so that the proper length will come to be considered “the” length. This situation is analogous to the earlier shift in the meaning of “the” mass.

In relativity, there are at least three different notions that can be used to describe vectors:

- a) The vector itself, considered as a geometric object in spacetime, existing independently from any observer and from any reference frame. (See Ref. 11.)
- b) The components of the vector, in some given reference frame.
- c) The snapshot length, i.e. the FitzGerald-Lorentz contracted length, which extends along the x direction in a given reference frame, but is not actually equal to the x component of the vector.

III. PROJECTIONS VERSUS DEJECTIONS

All projections considered in this article are orthogonal projections, whether or not we explicitly call them orthogonal.

The rule for making an orthogonal projection is as follows: to project an object onto a given axis, carry each point of the object along a contour *truly* perpendicular to the axis, until it reaches the axis.

Applying this rule correctly is slightly tricky on a spacetime diagram, because the geometry of the diagram-on-paper is not an entirely faithful representation of the *true* geometry of spacetime, as discussed in Ref. 10. Things that are truly perpendicular in spacetime may not look perpendicular on the diagram. For example, if you want to project something onto Moe’s x -axis (a red broken line in figure 2) you need to carry points along Moe’s contours of constant x (red solid lines in figure 2). On the right side of the diagram, they don’t look perpendicular on paper, but they are truly perpendicular in spacetime.

Specifically, if we project the heavy green bar onto Moe's x -axis, the result corresponds to the black arrow. The reverse is not true; the heavy green bar is *not* the projection of the black arrow onto Joe's x -axis. Instead we call the heavy green bar the *dejection* of the black arrow. (Logically and lexically this should probably be called the *rejection*, but mathematicians have already given that word a different geometrical meaning.)

An orthogonal projection in the xy plane always makes an image that is shorter than the original object (or possibly the same size).

A diagonal cut is always longer than the proper width of the material. This is a dejection, not a projection onto the observer's field of view.

An orthogonal projection in the tx plane always makes an image that is longer than the original object (or possibly the same size). Time dilation is an example of this.

A snapshot of a moving ruler is always shorter than the proper length of the ruler. The FitzGerald-Lorentz contraction is an example of this. This is a dejection, not a projection onto the observer's field of view.

IV. REALITY VERSUS APPEARANCE

We do not wish to have a philosophical debate about which notion of length is "real" or "correct." It is better to ask which notions are *useful* under what conditions. Someone who has truly mastered the subject should be able to see things from more than one point of view, switching back and forth when necessary.

It would be unwise to accept things as "real" if and only if they can be directly measured. That's because appearances can be deceiving. Oftentimes the important quantities can only be measured indirectly.

This point can be nicely illustrated using figure 3. This is a "real" image of Saturn; it is not an artist's conception; it is not a fake. The image of the rings is highly elliptical; specifically, the major axis is about six times as long as the minor axis. This is what our direct measurements are telling us.

Meanwhile we would say that in "real" space, the "real" rings are very nearly circular. The pronounced eccentricity of the image is a property of the image, not a property of the "real" rings.



FIG. 3: Image of Saturn

On the left side of figure 2, the proper width is *at least* as useful and as “real” as the length of a diagonal cut.

On the right side of figure 2, the proper length of a ruler is *at least* as useful and as “real” as the FitzGerald-Lorentz contracted length.

V. INTRINSIC VERSUS PROJECTIVE

Let us consider the notorious “pole in a barn” problem that crops up in many textbook discussions of relativity. The scenario calls for a pole-vaulter carrying a pole, running at relativistic speed through a barn. The proper length of the pole is comparable to the proper length of the barn. The textbook alleges that in the frame of the barn, “the” length of the pole is FitzGerald-Lorentz contracted, so that the pole definitely fits inside the barn ... whereas in the frame of the runner, the textbook alleges that the barn is contracted, so that the pole definitely does not fit.

It is amusing to compare the pole-and-barn system to the Saturn ring system (figure 3). In each system, there is a masochistic way and a sensible way to describe what is happening.

Saturn's rings are made of innumerable tiny orbiting particles. A masochist could, presumably, write down equations describing the motion of the particles' images in the plane of the image ... but these equations would be bizarrely complex.

One would need to explain why the particles appear to accelerate and decelerate as they go around the ellipse. One would also need to explain why the eccentricity of the ellipse changes from month to month.

The more sensible approach is to focus attention on the intrinsic (not projective) properties of the ring system. The description of the nearly-circular motion in the plane of the rings is incomparably simpler.

In either system, once we have an intrinsic description, it is straightforward to project it onto the axes of this-or-that observer.

We mention this because – hitherto – people have not sufficiently appreciated the importance of intrinsic properties (as opposed to projective properties) when discussing the pole-and-barn, the skateboard-and-manhole, and a host of similar problems.

A masochist could analyze the pole and barn using the textbook approach, using the projected (i.e. contracted) lengths.

The more sensible approach is to focus attention on the intrinsic (not contracted) properties of the pole-and-barn system. Draw a spacetime diagram. Don't talk about the pole being inside the barn at a particular time, since contours of constant time differ from one reference frame to another. Instead, focus attention on four-dimensional *events*.

It is hard to imagine anyone masochistic enough to analyze ring-particles in the plane of the image.

People are being taught to do correspondingly masochistic things in spacetime. They are being taught that moving rulers contract, and moving clocks run slow. This makes relatively seem incomparably more weird and difficult than it really is.

In summary, there are rather strong reasons why it is usually advantageous to focus attention on intrinsic properties such as proper time and proper length.

- The invariance of length with respect to boosts is consistent with the well-established invariance of length with respect to rotations.
- It allows the physics to be expressed more simply.
- Students can use their intuition about ordinary geometry to understand special relativity, and even general relativity.
- Conversely, exposure to spacetime and four-dimensional vectors reinforces and deepens students' understanding of ordinary geometry and three-dimensional vectors.

VI. TRAVELING TWINS

We now use what we know about length to help us understand time.

We start with a variation on the story of the notorious twins, Joe and Moe. They travel from event A to event D , each in his own car. Each car is equipped with an odometer and a clock. All the clocks and odometers are set to zero at the start of the trip.

A. Odometer-Distance versus Chord-Distance

At the end of the journey, Moe's odometer shows a greater reading than Joe's. There are two contrasting ways of explaining this result.

- a) It could be that Moe's odometer is faulty, and records some weird "contracted" units of distance.
- b) A far simpler explanation is that both odometers are functioning correctly, and that Moe took the scenic route, while Joe took the direct route.

Explanation (b) is familiar to us, in our non-relativistic travels through ordinary Euclidean space. Some paths are longer than others. Some instruments (notably rulers) are meant to be rigid, so that they measure the invariant distance between A and D . Meanwhile, other instruments (notably odometers) are meant to measure the path-length. Other instruments (notably measuring tapes) can be used either way.

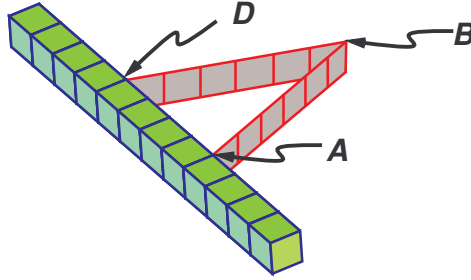


FIG. 4: Odometer versus Ruler

The distinction is portrayed in figure 4. Joe takes the direct path from A to D , so he can measure the length using a rigid ruler. Meanwhile, Moe takes the scenic route. The distance that he travels can be measured by an odometer, or equivalently by a flexible measuring tape that conforms to his path ABD .

As a useful bit of terminology, everyone (including Moe) can say that the ruler in figure 4 measures the *chord length*, i.e. the length of the chord drawn from point A to point D . Chord length stands in contrast to the proper length of Moe’s path ABD , aka the arc length. Chord length is equal to path length if and only if the path is straight; this effectively defines what we mean by “straight.”

B. Clock-Time versus Chord-Time

The story of the traveling twins becomes even more interesting when we look at the clocks. Moe’s clock shows less elapsed time than Joe’s.

- a) It could be that Moe’s clock is faulty, and records some weird “dilated” units of time.
- b) A far simpler explanation is that both clocks are functioning correctly, and that Moe took the scenic route through spacetime, while Joe took the direct route.

In the remainder of this section, we adopt description (b). We are not suggesting that description (a) is wrong; we just find description (b) vastly more convenient and more elegant.

In spacetime, clock readings are path-dependent for the same reason that odometer readings are path-dependent.

The geometry of spacetime¹⁰ is such that the scenic route will always rack up *more* mileage and *less* elapsed time than the direct route. [In some sense this defines what we mean by the *direct* route. This is related to the principle of least time (in geometrical optics) and the method of stationary phase (in wave mechanics and quantum mechanics), but details are beyond the scope of this article.]

This description has the virtue of consistency. In spacetime, we find it convenient to treat time on the same footing as space, and we find it convenient to treat boosts on the same footing as rotations.¹⁰ Just as viewing a ruler end-on does not change “the” length, viewing a fast-moving clock does not change “the” time between clock-ticks. The projection onto our frame of reference may be foreshortened or dilated, but this is just a property of the projection, not a property of the rulers or clocks themselves.

Naive nonrelativistic experience suggests that the elapsed time between event A and event D is independent of the path. This is true in the non-relativistic limit, but it is not true in general. We can say the same thing more graphically, using a spacetime diagram: elapsed time is path-independent if all observers’ world lines are very nearly parallel, but not if larger angles are involved. If relativistic speeds are involved, elapsed time is path-dependent in the same way that odometer readings are path-dependent.

Many textbooks put forth an argument of the following form: “Moe’s clock racks up less elapsed time, therefore it must have been running more slowly.” This argument is invalid, since it is based on the false assumption that the correct elapsed time would be path-independent.

Let’s be clear: Yes, at the end of the journey, Moe is younger than Joe (assuming they started out with equal ages). No, this does not prove that Moe’s clock ran slower. A far simpler explanation is that Moe took a less time-consuming path.

Another line of argument starts by considering events called *clock ticks*. Each tick is an *event* in the technical sense of the word, meaning it occurs at a definite place and a definite time in spacetime. We take it as the defining property of a well-behaved clock that

it produces clock-ticks at a uniform rate, according to an observer at rest with respect to the clock. This definition certainly upholds the correspondence principle.

A set of such clock-ticks is indicated by the red circles in figure 2, near the left edge of the spacetime diagram. These were produced by a clock at rest in Moe’s frame.

The usual argument asks us to calculate

$$\Delta t / \Delta \tau = \gamma \tag{5}$$

where τ is Moe’s proper time, and t is the time in Joe’s reference frame. You can calculate this quantity geometrically using figure 2, as follows: As Moe travels from one red circle to the next, his clock ticks off one unit of “red” time, so $\Delta \tau = 1$. Meanwhile, the projection of the vector onto Joe’s t axis is 13% longer than that. That is, Joe must wait *more* than one unit of “blue” time between the same two events.

If we calculate the same thing algebraically, we find $\Delta t / \Delta \tau = \cosh(\rho)$, which is also called γ . Everybody agrees on how to do this calculation . . . but often the result is encrusted with layers of metaphysics and questionable interpretations. In particular, intro-level textbooks commonly conclude from this that Moe’s clock is running slower . . . but any such conclusion is highly questionable. A far simpler interpretation is that Moe’s clock is keeping time just as it should, and that $\Delta t / \Delta \tau$ merely describes the projection from Moe’s frame onto Joe’s frame.

The ratio $\Delta t / \Delta \tau$ is a property of the projection, not a property of anybody’s clock. In particular, it is an orthogonal projection (like the rings in figure 3), not a dejection (like the heavy green bars in figure 2). As mentioned in section III, projections have the property that a foreshortened ruler always appears *shorter* than its proper length, while the time between ticks of a moving clock always appears *longer* than the proper time.

In analogy to chord length, we can define a notion of chord time, namely the time ticked off by a clock that moves from point A to point D along an unaccelerated world line, i.e. a straight line on the spacetime diagram. We coin the name *chordochronometer* for an instrument that measures this quantity. Chord time is equal to proper time if and only if the path is unaccelerated. Ref. 13 gives some formulas for calculating chord time.

The notion of “the” spacetime interval is widely used in the literature, but is ambiguous. We prefer to speak of the chord length and chord time, for reasons discussed in Ref. 10.

C. “Natural” Notions of Distance and Time

We emphasize that ruler distance and odometer distance are two well-defined, useful concepts . . . they just don’t happen to be the *same* concept. Each has a frame-independent definition (unlike Lorentz-contracted length, which pertains to a particular observer).

The relationship between ruler distance and odometer distance can be clearly seen if we consider a trip consisting of many steps. Let the i th step be described by a short vector, s_i . Then we have:

$$\text{ruler distance} = \left| \sum_i s_i \right| \tag{6a}$$

$$\text{odometer distance} = \sum_i |s_i| \tag{6b}$$

That is, the only difference is whether you sum before you take the norm, or take the norm before you sum. It would be silly to suggest that either of these is more “real” or more “physical” than the other.

The most complete and most “physical” description of the path is to specify all the short vectors, s_i . Each such vector is *local* to the path, *intrinsic* to the path, presumably *directly measurable*, and *independent* of the choice of reference frame. Given the entire sequence (s_1, s_2, \dots) , you have a complete description of the path. From there, you can summarize the data in various ways (ruler distance and/or odometer distance and/or whatever). Any such summary gives a less-than-complete description.

As you travel along your path, you are permitted to keep a running estimate of the ruler distance and/or odometer distance . . . but you are not required to.

The ruler distance has the nice simplifying property that it depends only on the endpoints of the path. It is just the ordinary distance between the endpoints, which can be calculated without knowing any other details of the path.

It is straightforward to build an odometer for a wheeled vehicle; you don’t need to do much more than count the revolutions of a wheel. It is a more challenging – conceptually as well as technically – to keep track of path length and/or chord length along an arbitrary path through spacetime. The usual name for a device that does this is *inertial navigation system* (INS). An INS needs one brief peek at an external reference, so it can know its initial position and velocity, but thereafter it does not depend on external references.

An INS can be concisely described by saying it finds the velocity by integrating the acceleration, and then finds the position by integrating the velocity. That’s true, if correctly interpreted. Obviously the velocity of interest (call it v) is not Moe’s velocity relative to Moe’s reference frame, since by definition Moe’s 4-velocity always has components $[1, 0, 0, 0]$ in that frame. Instead, realize that the INS displays position relative to some chosen unaccelerated reference point, and v is Moe’s velocity relative to that point. There is no such thing as absolute position or absolute velocity, but absolute acceleration is well defined and readily measurable. Moe can integrate his acceleration to keep an up-to-date estimate of v , and integrate v to get the position relative to the reference point.

VII. PEDAGOGICAL IMPLICATIONS

1. We predict that the contracted/dilated approach will eventually die out in favor of the geometric approach. We hope this happens sooner rather than later. The geometric approach seems superior in every way, including simplicity, elegance, power, and consistency.
2. Until that happens, we should avoid asking whether “moving rulers are shorter” or “moving clocks are slower.” Non-experts generally answer yes, while experts answer no. Instead, we should say that *proper* length and *proper* time are invariant, so we can speak clearly about ideas, rather than wrangling over mere terminology.
3. The main physics ideas in this article have been well known since the dawn^{7,8} of relativity. Taylor and Wheeler⁹ explained the geometric approach with exemplary clarity, at a level that requires only algebra and a little bit of trigonometry. Ref. 10 argues that spacetime is as similar to ordinary space as it possibly could be, short of being entirely identical.
4. One big advantage of the geometric approach is backward compatibility, i.e. that it provides an opportunity to review, reinforce, and extend previously-learned ideas, for example as the idea of vector is extended to include 4-vectors, and the idea of rotation is extended to include boosts.
5. Another big advantage of the geometric approach is forward compatibility, i.e. that it prepares the students for more advanced studies. For instance, when we proceed from

special to general relativity, nobody takes seriously Feynman’s parable about rulers that change length from place to place; instead they describe everything in terms of invariant length and proper time. The watchword is, “Time is defined so that motion looks simple.”¹⁴

6. There is, alas, remarkably little support for the geometric approach in present-day introductory texts. A query addressed to 700 physics teachers via the **Phys-L** mailing list¹⁵ failed to turn up a single general-physics coursebook that emphasizes the geometric approach. (This counts only books intended to serve as the principal text in a high-school physics course or a first-year college physics course, as opposed to relativity-only books like Taylor and Wheeler.⁹)

The wide-ranging survey and analysis in Ref. 17 is valuable, but only tangentially connected to the topic of this article, since it concentrates on invariant (or non-invariant) notions of mass, rather than space and time.

The continued prevalence of the contracted/dilated approach is disappointing, and there does not appear to be any good reason for it. Simple inertia would be a good-enough argument in favor of tried-and-true techniques, but the contracted/dilated approach is so problematic that this argument does not apply. The physics-education research (PER) literature (e.g. Ref. 16) identifies “persistent difficulties” and finds that “Traditional instruction in relativity appears to have little effect on these ideas, which are present among students from the introductory to the graduate level in physics.” On the other side of the same coin, there appears to be virtually no published PER comparing the geometric approach to the contracted/dilated approach. Ref. 16 mentions *Spacetime Physics*⁹ only in connection with an elective relativity course offered to advanced students. Even then, “Both introductory and advanced courses emphasized length contraction,” leaving us with no information about the merits of emphasizing invariant length.

In the absence of systematic observations, there are powerful plausibility arguments in favor of the geometric approach, based on well-established pedagogical principles, such as simplicity, elegance, power, and consistency; see also item 10 below.

7. A hard-line manifesto opposing the geometric interpretation can be found in Ref. 18.
8. The history of science is a poor guide to the teaching of science. Good pedagogy is

logical and straightforward, whereas the historical record contains much backtracking out of blind alleys. Especially in an introductory course, students should be given the *best* explanation for each idea, which is rarely the same as the most ancient explanation. Einstein came to special relativity via a difficult route . . . but that does not mean present-day students must follow the same route, when an easier and more elegant route – the geometric approach – is readily available. There is no reason why pedagogy must recapitulate phylogeny.

For what it’s worth: After the geometric approach became available, Einstein adopted it, and relied on it during the development of general relativity. That is a useful hint. Any such appeal to authority must be considered weak evidence, but it is harmless in this case, because it agrees with conclusions we have already reached via other, stronger arguments.

We are not constrained by the history of *who* did this-or-that. Instead, we should focus on the *reasons* for doing this-or-that, and judge the reasons on their merits.

9. There is a profound analogy between time and space, and it is often very helpful to exploit this analogy. However, as the proverb says, no matter what you are doing, you can always do it wrong. We should beware of situations where some timelike concept is associated with a *non-corresponding* spacelike concept.

- As an example: time dilation and FitzGerald-Lorentz contraction are commonly mentioned in the same breath, but alas they are not corresponding concepts, for reasons discussed in section III and Ref. 19. This can be misleading to students, making the geometry of spacetime¹⁰ seem less simple than it really is.
- As a different but equally misleading example: clocks and rulers are often mentioned in the same breath, but are not corresponding concepts (except in the less-than-general case of unaccelerated motion). Some closer correspondences are:

Space is to time
as odometer is to clock
and as rigid ruler is to chordochronometer.

10. The traditional approach to teaching relativity emphasizes that it is weird and rife with paradoxes, using rulers that can’t be trusted and clocks that can’t be trusted. In

contrast, we believe that it is pedagogically better to teach students that relativity is not particularly weird or paradoxical; indeed it is in many ways closely analogous to the geometry of ordinary Euclidean space.

In particular, the FitzGerald-Lorentz contraction is the spacetime version of a deformation, in analogy to a diagonal cut across a piece of fabric. Similarly, time dilation is the spacetime version of a simple orthogonal projection, in analogy to the elliptical image of the rings of Saturn.

VIII. SUMMARY

The way relativity has heretofore been taught to the general population – and to the next generation of physics teachers – makes things seem far more complicated than they really are. It is out of step with the way experts think about the subject, and has been for many decades. It is not technically wrong, just pedagogically inferior to the geometric approach.

We call attention to a pair of simple yet powerful ideas: treating time and space on the same footing, and treating boosts and rotations on the same footing. This gives us a nice way of visualizing special relativity:

- As everybody knows, the length of a ruler is invariant under rotations.
- That tells us the length of a ruler is invariant under boosts.
- In turn, that tells us the time between ticks of an ordinary clock is invariant under boosts (and rotations).

The defining property of an ordinary clock is that it ticks at a steady rate, marking off uniform intervals of proper time. An ordinary clock carried on a journey behaves more like an odometer than a rigid ruler, recording proper time, not chord time. If you want to know the chord time, you need to carry something more complicated than an ordinary clock, i.e. something like an INS.

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